# Monday, February 10

Mathematical (statistical) models make *assumptions*, and results (statistical inferences) based on the models are derived using those assumptions.

Example: Assume that an object is a cone. It can be shown (with a little calculus) that

$$\mathbf{V} = \pi r^2 h/3$$
 and  $\mathbf{A} = \pi r \left( r + \sqrt{r^2 + h^2} \right)$ ,

based on the assumption that the object is a cone.

"All models are wrong but some are useful." — George E. P. Box

## Implicit Assumptions of Linear and Nonlinear Regression

Discussions of assumptions are based on an alternative representation of a regression model. A linear model can be written as

 $Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + \epsilon_i,$ 

and a nonlinear model can be written as

$$Y_i = f(x_{i1}, x_{i2}, \dots, x_{ik}) + \epsilon_i,$$

where the linear model with

$$f(x_{i1}, x_{i2}, \dots, x_{ik}) = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik}$$

is a special case.

There are four implicit assumptions about  $\epsilon_i$  that go into the derivation of routine/default methods for making inferences concerning the model.

- 1.  $E(\epsilon_i) = 0$  for all i.
- 2.  $Var(\epsilon_i) = \sigma^2$  for all *i*.
- 3.  $Cov(\epsilon_i, \epsilon_{i'}) = 0$  for all  $i \neq i'$ .
- 4. Each  $\epsilon_i$  has a normal distribution.

How should we approach each assumption?

- 1. How do we *define* each assumption?
- 2. What are the *consequences* if the assumption is (very) wrong?
- 3. How do we *detect* if the assumption is (very) wrong?
- 4. What is/are the solution(s) if the assumption is (very) wrong?

#### **Assumption 1: Zero Expectations of Errors**

**Definition**: The assumption  $E(\epsilon_i) = 0$  implies that  $E(Y_i)$  depends on the explanatory variables in the way assumed by the model. That is, if we have the *assumed* model

$$E(Y_i) = f(x_{i1}, x_{i2}, \dots, x_{ik})$$

then

$$E(\epsilon_i) = 0 \Rightarrow E(Y_i) = f(x_{i1}, x_{i2}, \dots, x_{ik}).$$

For the model to be a correct representation of the relationship between  $E(Y_i)$  and  $x_{i1}, x_{i2}, \ldots, x_{ik}$  we require that  $E(\epsilon_i) = 0$  for all  $i = 1, 2, \ldots, n$ .

Consequences: Estimates of parameters or some functions thereof (e.g., linear combinations) may be biased.

**Detection**: *Residuals* are statistics that are frequently used to *empirically* investigate assumption violations. There are several types of residuals.

1. Raw residuals. These are simply estimates of  $\epsilon_i$ . In a linear model, for example, the error is

$$\epsilon_i = Y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_k x_{ik}),$$

by definition, so a simple estimator of  $\epsilon_i$  is the *residual* 

$$e_i = Y_i - \hat{Y}_i,$$

where

$$\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \dots + \hat{\beta}_k x_{ik}.$$

We can define the raw residual in a similar way for a nonlinear model.

2. Standardized residuals. Defined as

$$z_i = \frac{e_i}{\operatorname{SE}(e_i)}.$$

If the model assumptions are *correct* then  $z_i$  is *approximately* standard normal in distribution so we expect that about 95% of such residuals to satisfy  $|z_i| < 2$ .

3. Studentized residuals. Defined as

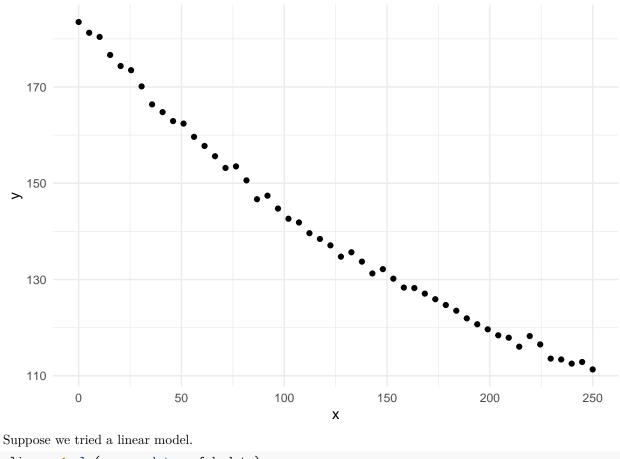
$$t_i = \frac{e_i}{\operatorname{SE}_{(i)}(e_i)}$$

where  $\text{SE}_{(i)}(e_i)$  is the standard error of  $e_i$  estimated by *leaving out* that observation. This avoids bias in the standard error in cases where  $E(\epsilon_i) \neq 0$ . If the model assumptions are met then each  $t_i$  has a tdistribution with one less degree of freedom than the residual degrees of freedom (i.e., n - p - 1 where p is the number of *parameters* in the model). Unless n - p - 1 is very small, we expect that about 95% of studentized residuals satisfy  $|t_i| < 2$ .

What to look for in residuals:

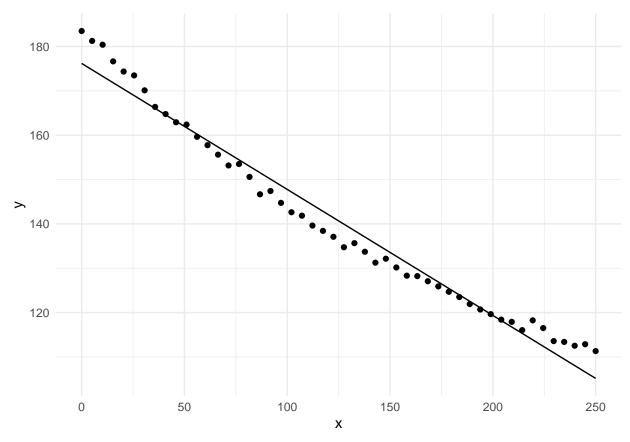
- 1. Individual observations with exceptional residuals.
- 2. More residuals than expected overall that are exceptional.
- 3. Changes in the distribution of residuals when plotting against  $\hat{y}_i$ .

**Example**: Consider the following artificial data.



```
mlinear <- lm(y ~ x, data = fakedata)
fakedata$yhat <- predict(mlinear)  # y-hat values
fakedata$rese <- residuals(mlinear)  # raw residuals
fakedata$rest <- rstudent(mlinear)  # studentized residuals
head(fakedata)</pre>
```

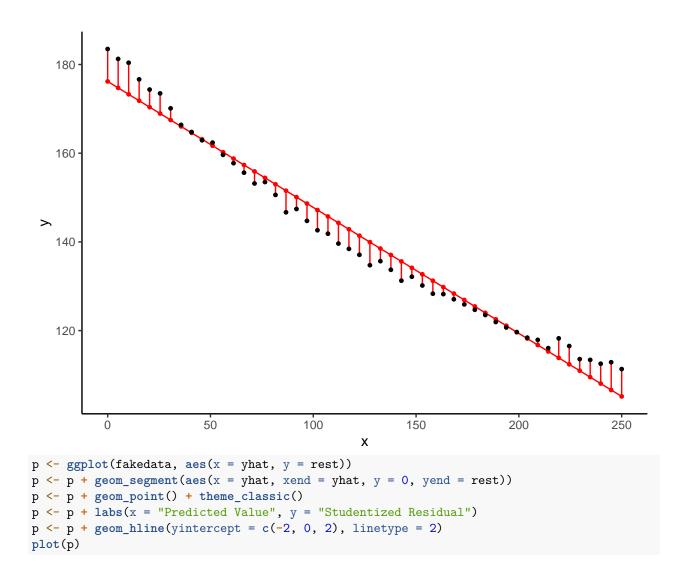
x y yhat rese rest 1 0.000 183.5 176.2 7.311 2.198 2 5.102 181.3 174.7 6.525 1.936 3 10.204 180.4 173.3 7.113 2.121 4 15.306 176.6 171.8 4.813 1.396 5 20.408 174.4 170.4 3.964 1.140 6 25.510 173.5 168.9 4.547 1.311 p <- p + geom\_line(aes(y = yhat), data = fakedata) plot(p)

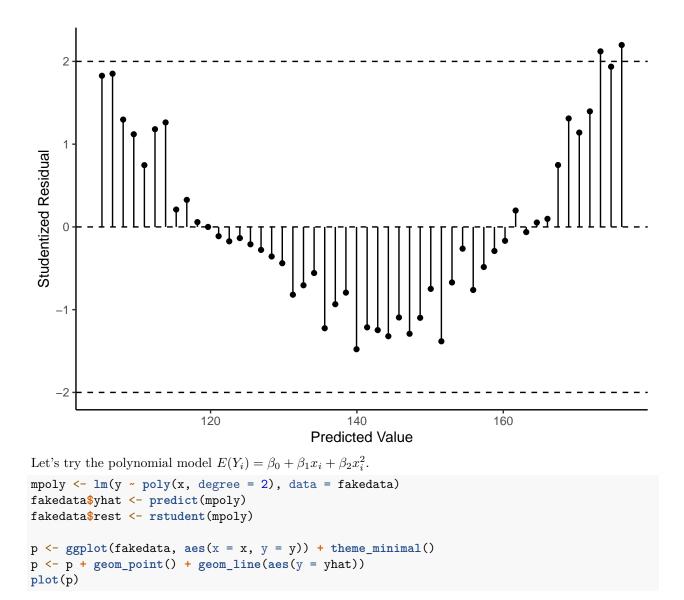


What are the observations with "exceptionally large" residuals?

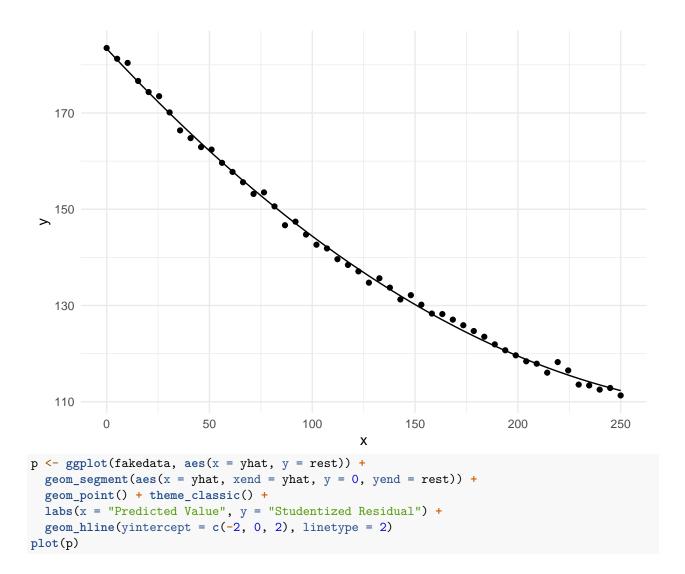
subset(fakedata, abs(rest) > 2)
 x y yhat rese rest
1 0.0 183.5 176.2 7.311 2.198
3 10.2 180.4 173.3 7.113 2.121
library(dplyr)
fakedata %>% filter(abs(rest) > 2)
 x y yhat rese rest
1 0.0 183.5 176.2 7.311 2.198
2 10.2 180.4 173.3 7.113 2.121

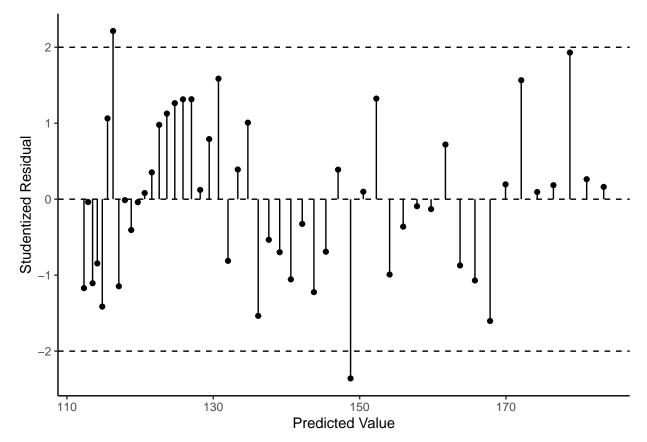
Are there any patterns?





```
6
```



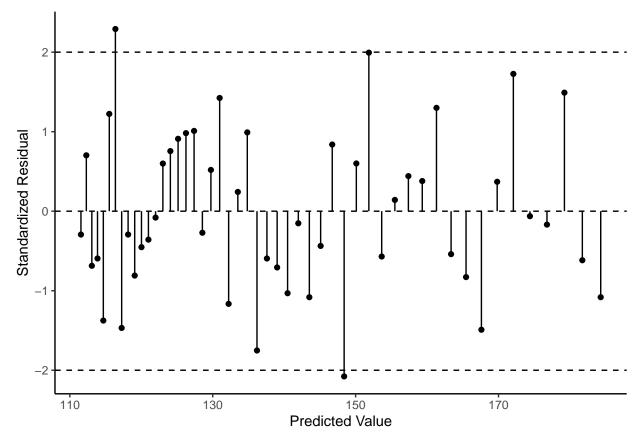


The "correct" model is the nonlinear model

$$E(Y_i) = \alpha + (\delta - \alpha)2^{-x_i/\gamma}.$$

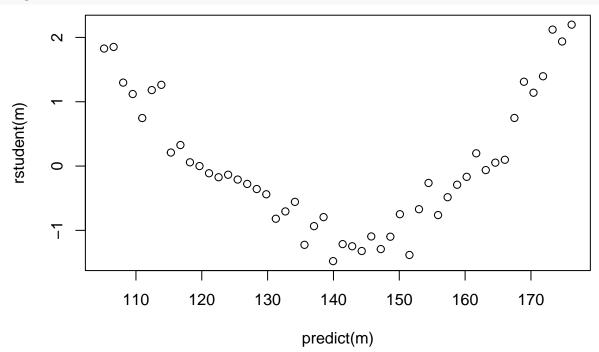
```
mnlin <- nls(y ~ alpha + (delta - alpha) * 2^(-x / gamma),
    data = fakedata, start = list(alpha = 80, delta = 180, gamma = 140))
library(trtools) # for the nlsint function
d <- nlsint(mnlin, residuals = TRUE)
head(d)
    fit se lwr upr hat res
1 184.3 0.3894 183.5 185.1 0.21231 -1.08147
2 181.7 0.3481 181.0 182.4 0.16966 -0.61684
3 179.2 0.3112 178.6 179.9 0.13564 1.49073
4 176.8 0.2788 176.2 177.3 0.10888 -0.16877
```

```
5 174.4 0.2510 173.9 174.9 0.08820 -0.06274
6 172.1 0.2276 171.6 172.5 0.07256 1.72687
p <- ggplot(d, aes(x = fit, y = res)) +
  geom_segment(aes(x = fit, xend = fit, y = 0, yend = res)) +
  geom_point() + theme_classic() +
  labs(x = "Predicted Value", y = "Standardized Residual") +
  geom_hline(yintercept = c(-2, 0, 2), linetype = 2)
plot(p)</pre>
```

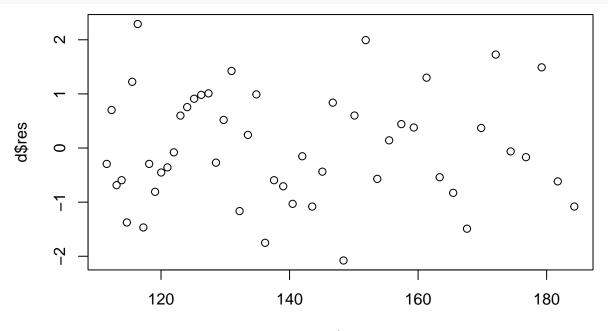


Note that since we are usually not interested in created publication quality residual plots, we can do some quick-and-dirty plots with simpler (but uglier) graphics.

# when using lm
m <- lm(y ~ x, data = fakedata)
plot(predict(m), rstudent(m))</pre>



```
# when using nls
mnlin <- nls(y ~ alpha + (delta - alpha) * 2^(-x / gamma),
    data = fakedata, start = list(alpha = 80, delta = 180, gamma = 140))
d <- nlsint(mnlin, residuals = TRUE) # nlsint is from trtools package
plot(d$fit, d$res)</pre>
```



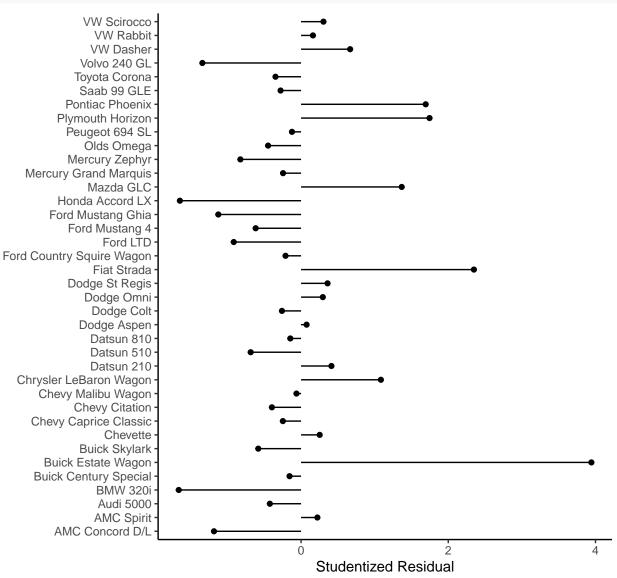
d\$fit

**Example**: Consider a model where the expected MPG of cars is assumed to be a linear function of weight and rear axle ratio.

```
cars <- read.csv("http://webpages.uidaho.edu/~trjohns/cars.csv")
cars <- cars[,c(2,3,4,5)] # select columns 2, 3, 4, and 5
head(cars)</pre>
```

```
car mpg weight ratio
1
         Buick Estate Wagon 16.9 4.360 2.73
2 Ford Country Squire Wagon 15.5 4.054 2.26
3
         Chevy Malibu Wagon 19.2 3.605 2.56
4
     Chrysler LeBaron Wagon 18.5 3.940 2.45
5
                   Chevette 30.0 2.155 3.70
6
              Toyota Corona 27.5 2.560 3.05
m <- lm(mpg ~ weight + ratio, data = cars)</pre>
cars$yhat <- predict(m)</pre>
cars$rest <- rstudent(m)</pre>
subset(cars, abs(rest) > 2)
                  car mpg weight ratio yhat rest
1 Buick Estate Wagon 16.9
                             4.36 2.73 10.32 3.944
          Fiat Strada 37.3
                             2.13 3.10 32.67 2.348
34
p <- ggplot(cars, aes(x = rest, y = car)) + geom_point() +</pre>
 theme_classic() +
  geom_segment(aes(x = 0, xend = rest, y = car, yend = car)) +
 labs(x = "Studentized Residual", y = NULL)
```

### plot(p)



What is up with the Buick Estate Wagon?

**Solutions**: Modify the model. Drop offending obsrevations(s) if and only if you can justify restricting the scope of the model.

# Assumption 2: Equality of Error Variances

**Definition**: In the regression model

$$Y_i = f(x_{i1}, x_{i2}, \dots, x_{ik}) + \epsilon_i,$$

we assume  $\operatorname{Var}(\epsilon_i) = \sigma^2$  which implies  $\operatorname{Var}(Y_i) = \sigma^2$ . This is called "homoscedasticty" or sometimes "homogeneity of variance" in the context of linear models for designed experiments. A more complete description of the assumed model is

$$E(Y_i) = f(x_{i1}, x_{i2}, \dots, x_{ik}),$$
(1)

$$\operatorname{Var}(Y_i) = \sigma^2. \tag{2}$$

Note that the estimator  $\hat{\sigma}^2$ , the square of the "residual standard error" reported by summary, is computed as

$$\hat{\sigma}^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n - p}$$

where p is the number of parameters in the part of the model for  $E(Y_i)$  (which is p = k + 1 in a linear model with a  $\beta_0$  term and k explanatory variables).

Consequences: Severe violations of homoscedaticity can result in two problems.

- 1. Biased standard errors, incorrect p-values, and incorrect confidence/prediction intervals.
- 2. Inefficient estimation of model parameters (and functions thereof).

**Detection**: Many common patterns of heteroscedasticity can be found by plotting standardized or studentized residuals against  $\hat{y}_i$ .

**Example**: Consider the following data on survival time of terminal cancer patients given a supplement of ascorbate (i.e., vitamin C).

```
library(Stat2Data)
data(CancerSurvival) # this package requires that we "load" the data
head(CancerSurvival)
```

```
Survival Organ
1 124 Stomach
2 42 Stomach
3 25 Stomach
4 45 Stomach
5 412 Stomach
6 51 Stomach
```

For plotting purposes we can order the levels of Organ according to mean survival using reorder.

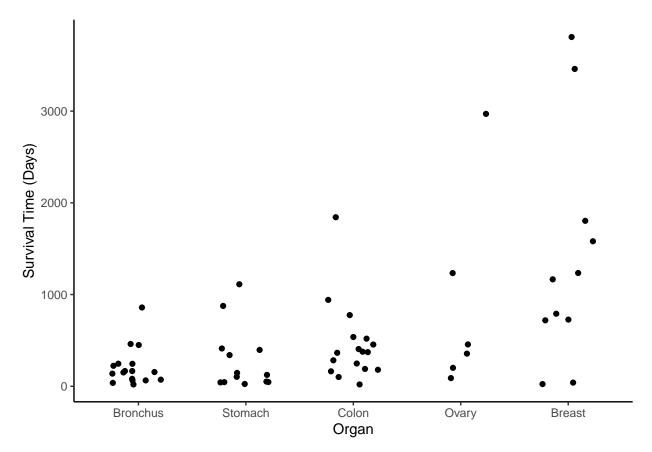
```
CancerSurvival$Organ <- with(CancerSurvival, reorder(Organ, Survival, mean))</pre>
```

The with function implies that each variable is "with" the data frame CancerSurvival. This is sometimes nicer than having to identify the data frame explicitly as in the following.

```
CancerSurvival$Organ <- reorder(CancerSurvival$Organ, CancerSurvival$Survival, mean)
```

Here is a plot of the data using geom\_jitter to space out the points.

```
p <- ggplot(CancerSurvival, aes(x = Organ, y = Survival)) +
geom_jitter(height = 0, width = 0.25) +
labs(y = "Survival Time (Days)") + theme_classic()
plot(p)</pre>
```



Here we can see some descriptive statistics.

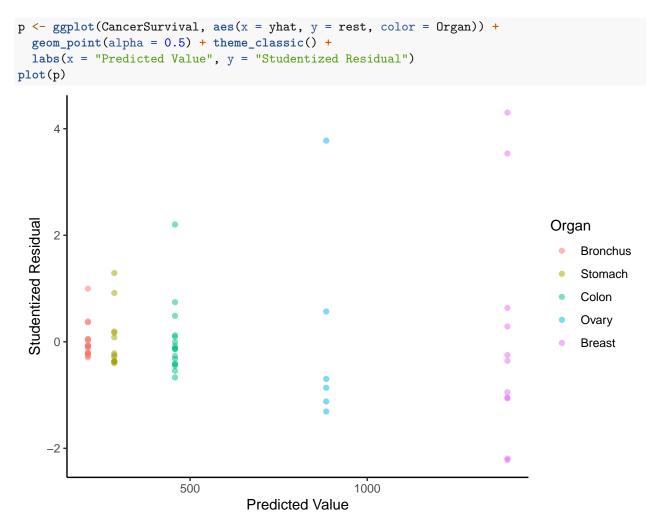
```
library(dplyr)
CancerSurvival %>% group_by(Organ) %>%
summarize(mean = mean(Survival), stdev = sd(Survival), obs = n())
```

```
# A tibble: 5 x 4
  Organ
             mean stdev
                           obs
  <fct>
            <dbl> <dbl> <int>
1 Bronchus
            212.
                   210.
                            17
2 Stomach
             286
                   346.
                            13
3 Colon
             457.
                   427.
                            17
            884. 1099.
                             6
4 Ovary
5 Breast
            1396. 1239.
                            11
```

Now consider a linear model that assumes homoscedasticity.

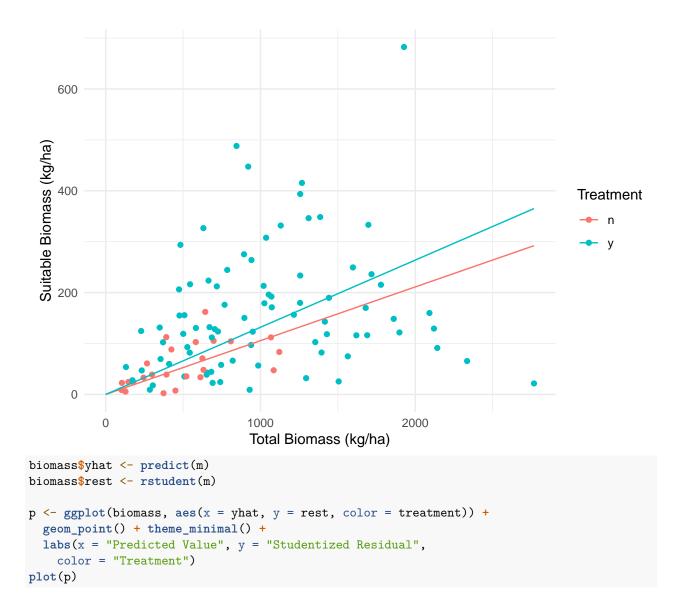
```
m <- lm(Survival ~ Organ, data = CancerSurvival)
CancerSurvival$yhat <- predict(m)
CancerSurvival$rest <- rstudent(m)
head(CancerSurvival)</pre>
```

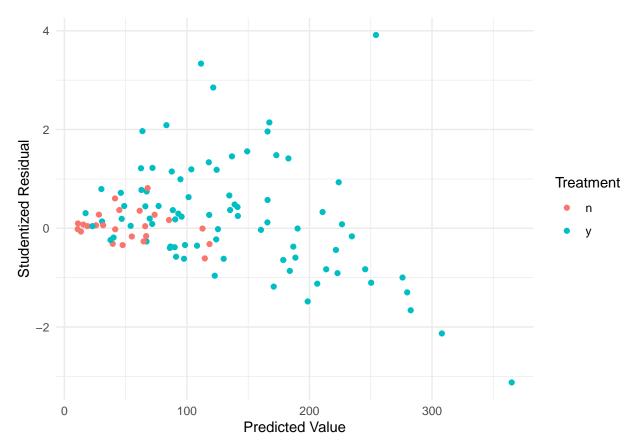
Organ yhat Survival rest124 Stomach 286 -0.2498 1 2 42 Stomach 286 -0.3765 3 286 -0.4029 25 Stomach 4 45 Stomach 286 -0.3719 5 412 Stomach 286 0.1943 6 51 Stomach 286 -0.3626



**Example**: Consider the following data from a study on the effects of fuel reduction on biomass.

```
library(trtools) # for biomass data
m <- lm(suitable ~ -1 + treatment:total, data = biomass)</pre>
summary(m)$coefficients
                  Estimate Std. Error t value Pr(>|t|)
treatmentn:total
                    0.1056
                              0.04183
                                        2.524 1.31e-02
treatmenty:total
                    0.1319
                              0.01121 11.773 7.61e-21
d <- expand.grid(treatment = c("n","y"), total = seq(0, 2767, length = 10))</pre>
d$yhat <- predict(m, newdata = d)</pre>
p <- ggplot(biomass, aes(x = total, y = suitable, color = treatment)) +</pre>
  geom_point() + geom_line(aes(y = yhat), data = d) + theme_minimal() +
  labs(x = "Total Biomass (kg/ha)", y = "Suitable Biomass (kg/ha)",
    color = "Treatment")
plot(p)
```





Solutions: There are several possible solutions.

- 1. Response variable transformation.
- 2. Weighted least squares.
- 3. Robust standard error estimators.
- 4. Models that do not assume constant variance.

We will discuss each of these in turn soon.